

MH-Z16
Intelligent Infrared Gas Module
Manual

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1 Profile



Main functions and features :

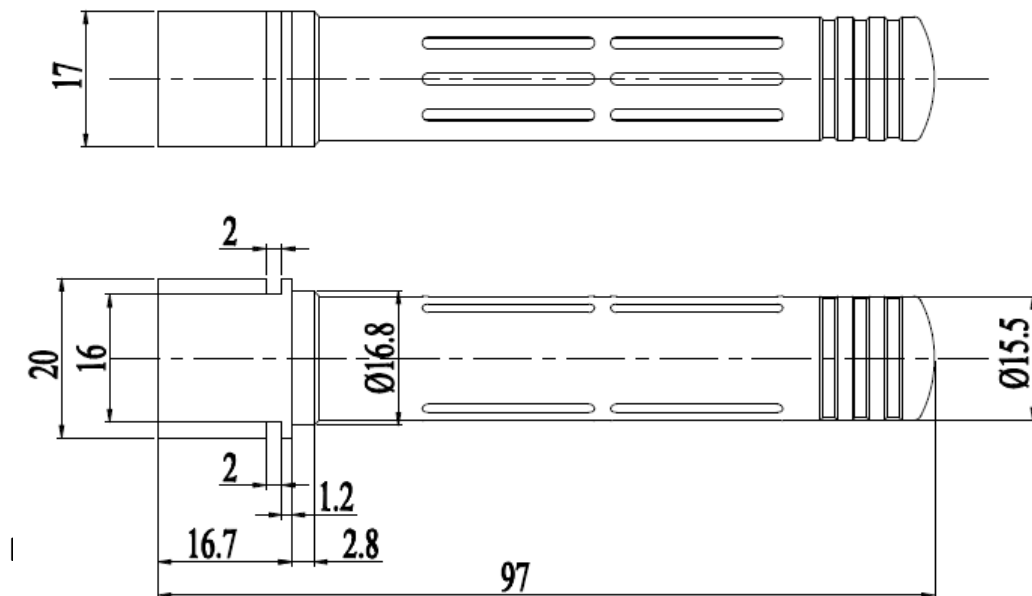
- High sensitivity, High resolution
- Low power consumption
- Output method: UART, analog voltage signal, PWM wave
- Quick response
- Temperature compensation, excellent linear output
- Good stability
- Long lifespan
- Anti water vapor interference
- No poisoning

2 Main technical parameters

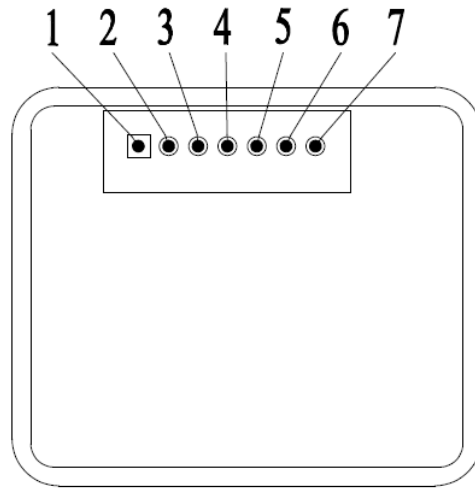
| | |
|---------------------|------------------|
| Working voltage | 4.5 V ~ 5.5V DC |
| Average current | < 85 mA |
| Interface level | 3.3 V |
| Measuring range | 0~5%VOL optional |
| Output signal | PWM UART |
| Preheat time | 3min |
| Reponse Time | $T_{90} < 30s$ |
| Working temperature | 0°C ~ 50°C |
| Working humidity | 0~95%RH |
| Weight | 21 g |
| Lifespan | >5 years |

| Target Gas | Measuring Range | Accuracy | Mark |
|-----------------------------------|-----------------|---------------------------|--------------------------|
| Carbon Dioxide (CO ₂) | 0~2000ppm | ±(50ppm +5%reading value) | Temperature compensation |
| | 0~5000ppm | | Temperature compensation |
| | 0~1%VOL | | Temperature compensation |
| | 0~3%VOL | | Temperature compensation |
| | 0~5%VOL | | Temperature compensation |

3.Structure

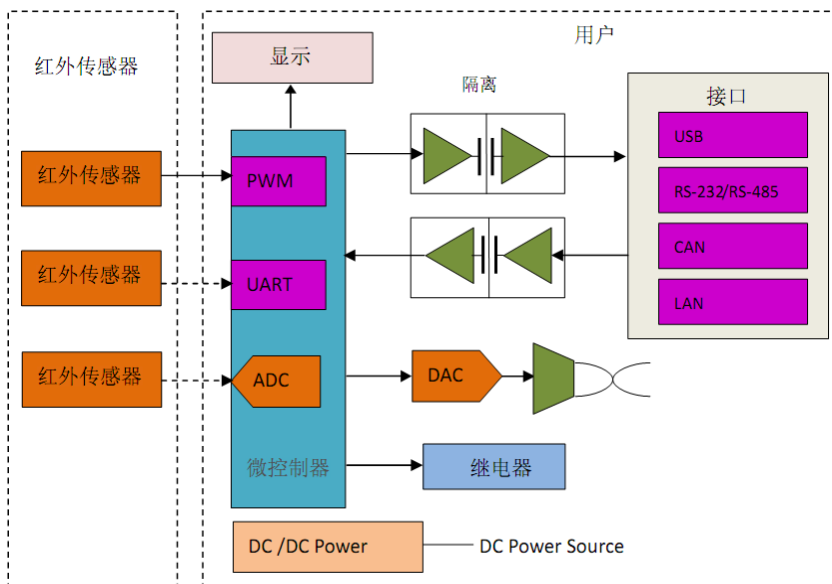


4.Pin



| PIN | Description |
|------|----------------------------------|
| Pad4 | Vin(input voltage 4.5V~5.5V) |
| Pad3 | GND |
| Pad2 | Vout (0.4~2V, custom made) |
| Pad7 | PWM |
| Pad1 | HD |
| Pad5 | UART (RXD) 0~3.3V input digital |
| Pad6 | UART (TXD) 0~3.3V output digital |

5.Circuit



6. Operating instruction

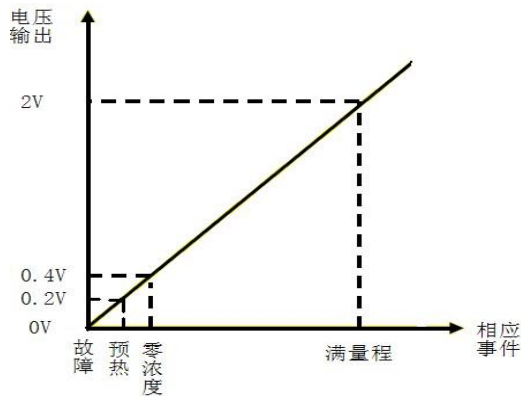
6.1 Analog output connections

The output value of V_{out} is 0.4-2.0V, which stands for 0 to full range

V_{in} -5V

GND- Power Ground

V_{out} -ADC input



6.2 PWM output (taking PWM output from 2000ppm as example):

CO2 output range: 0ppm-2000ppm

Cycle: 1004ms \pm 5%

High level output for beginning: 2ms (in name)

Middle of cycle: 1000ms \pm 5%

Low level output for ending: 2ms (in name)

Account formula for CO2 concentration which gets through PWM:

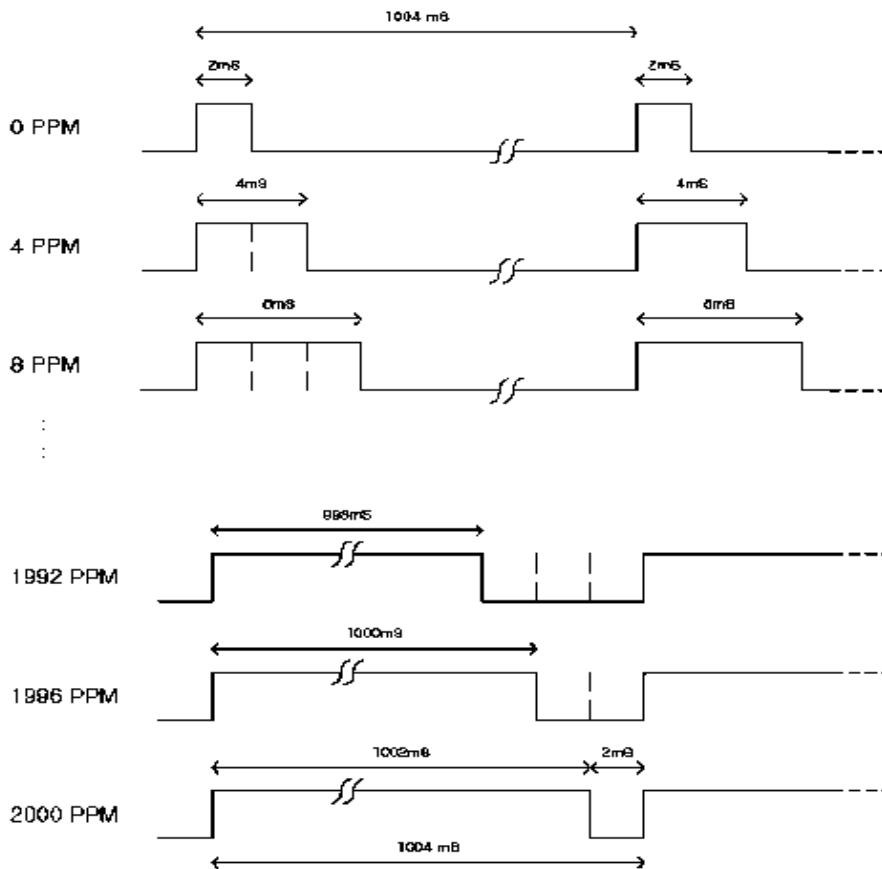
$$C_{ppm} = 2000 \times (T_H - 2ms) / (T_H + T_L - 4ms)$$

Among:

C_{ppm} is calculated CO2 concentration, unit is ppm;

T_H is time for high level during an output cycle;

T_L is time for low level during an output cycle.



6.3 Digital connects:

Vin-5V power

GND- Power Ground

RXD connect sensor TXD

TXD connect sensor RXD

You can read gas concentration via Uart, no need to calculate.

6.3.1 communication protocol

1.General Settings

| | |
|----------------|--------|
| Baud rate | 9600 |
| Date byte | 8 byte |
| Stop byte | 1byte |
| Calibrate byte | no |

2.Command

Each command or return:

Contains 9 bytes (byte 0 ~ 8)

starting byte fixed 0 XFF

command contains sensor number (factory default to 0 x01)
to check and end

Command List:

| | |
|------|-----------------------------|
| 0x86 | Gas concentration |
| 0x87 | Calibrate zero point (ZERO) |
| 0x88 | Calibrate span point (SPAN) |

Read gas concentration

| Send command | | | | | | | | |
|----------------------|---------------|---------|-------|-------|-------|-------|-------|----------------|
| Byte0 | Byte1 | Byte2 | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 | Byte8 |
| Start ing byte | Sensor No. | command | - | - | - | - | - | Check value |
| 0XFF | 0x01 | 0x86 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x79 |

Return value

| Return | | | | | | | | |
|----------------------|---------|------------------------------------|-----------------------------------|-------|-------|-------|-------|------------------------|
| Byte0 | Byte1 | Byte2 | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 | Byte 8 |
| Start ing byte | command | High level concentr ation | Low level concentr ation | - | - | - | - | Chec k valu e |
| 0XFF | 0x86 | 0x02 | 0x60 | 0x47 | 0x00 | 0x00 | 0x00 | 0xD1 |

Gas concentration= high level *256+low level

Calibrate zero point

| Send command | | | | | | | | |
|----------------------|---------------|---------|-------|-------|-------|-------|-------|----------------|
| Byte0 | Byte1 | Byte2 | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 | Byte8 |
| Start ing byte | Sensor No. | command | - | - | - | - | - | Check value |
| 0XFF | 0x01 | 0x87 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x78 |

No return value

Calibrate span point

| Send command | | | | | | | | |
|----------------------|---------------|---------|--------------------------------|-------------------------------|-------|-------|-------|----------------|
| Byte0 | Byte1 | Byte2 | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 | Byte8 |
| Start ing byte | Sensor No. | command | High level span point | Low level span point | - | - | - | Check value |
| 0XFF | 0x01 | 0x88 | 0x07 | 0xD0 | 0x00 | 0x00 | 0x00 | 0xA0 |

No return value

3. Calibrate and calculate

The checksum = (invert (byte 1 +... + 7)) + 1

Reading gas concentration:

| Send command | | | | | | | | |
|---------------|------------|---------|-------|-------|-------|-------|-------|-------------|
| Byte0 | Byte1 | Byte2 | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 | Byte8 |
| Starting byte | Sensor No. | command | - | - | - | - | - | Check value |
| 0XFF | 0x01 | 0x86 | 0x00 | 0x00 | 0x00 | 0x00 | 0x00 | 0x79 |

Except byte 0 ,add the other bytes together

$$0x1 + 0x86 + 0 + 0 + 0 + 0 + 0 + 0 = 0x87$$

Get the value from the first step, then invert it.

$$0xff - 0x87 = 0x78$$

The second value plus one

$$0x78 + 0x01 = 0x79$$

Program :C language

```
char getChecksum(char *packet)
{
    char i, checksum;
    for(i = 1; i < 8; i++)
    {
        checksum += packet[i];
    }
    checksum = 0xff - checksum;
    checksum += 1;
    return checksum;
}
```

7. Notes for maintenance

7.1 The sensor should be calibrated regularly. The cycle time is better to be no more than 6 months.

7.2 Do not use the sensor in the high dusty environment for long time.

7.3 Please use the sensor with correct power supply.

7.4 Forbidden to cut the sensor pin.

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